# Causal Discovery from Interventional Data Bachelor's Thesis

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### **Agenda**

- ${f 1.}$  Problems addressed by the thesis
- 2. Proposed methods
- 3. Simulation studies and results
- 4. Conclusion

### **Problem description**

**Goal**: Learn causes of response Y among covariates X. **Setting**: Two repetitions of the same set of experiments.

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#### Problems:

- **(A)** X and Y come from separate sets of experiments
- **(B)** We observe (X, Y) in both sets of experiments
- (C) We observe (X, Y) in a single set of experiments

### **Underlying SCM and shift interventions**

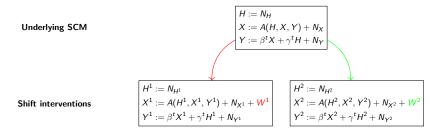
Underlying SCM

$$H := N_H$$

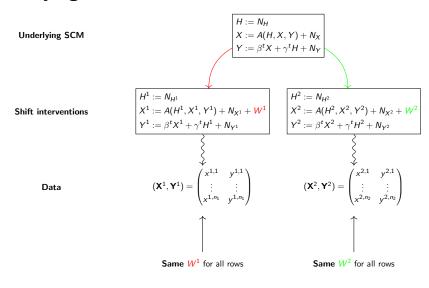
$$X := A(H, X, Y) + N_X$$

$$Y := \beta^t X + \gamma^t H + N_Y$$

#### **Underlying SCM and shift interventions**



### **Underlying SCM and shift interventions**



### Two repetitions of the same experiments

$$H := N_H$$

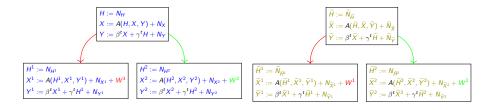
$$X := A(H, X, Y) + N_X$$

$$Y := \beta^t X + \gamma^t H + N_Y$$

$$\begin{split} \widetilde{H} &:= \widetilde{N}_{\widetilde{H}} \\ \widetilde{X} &:= A(\widetilde{H}, \widetilde{X}, \widetilde{Y}) + \widetilde{N}_{\widetilde{X}} \\ \widetilde{Y} &:= \beta^t \widetilde{X} + \gamma^t \widetilde{H} + \widetilde{N}_{\widetilde{Y}} \end{split}$$

**Same** underlying SCM **Different** noise variables

### Two repetitions of the same experiments

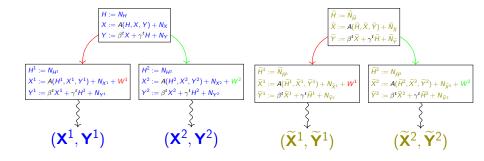


Same underlying SCM

Different noise variables

Same shift interventions

### Two repetitions of the same experiments



Same underlying SCM
Different noise variables
Same shift interventions
Two separate data sets
for each intervention

# More detailed problem description

**Goal**: Learn causes of response Y among covariates X.

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#### **Problems:**

- (A) X and Y come from separate sets of experiments (X, Y)
- **(B)** We observe (X, Y) in both sets of experiments  $(X, Y, \widetilde{X}, \widetilde{Y})$
- (C) We observe (X, Y) in a single set of experiments (X, Y)

# Strategy for single experiment problem

#### Permute rows to turn one data set into two:

With permutation matrices  $P^1$  and  $P^2$ , let

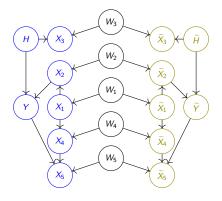
$$(\mathbf{X},\mathbf{Y}) = \begin{pmatrix} \mathbf{X}^1 & \mathbf{Y}^1 \\ \mathbf{X}^2 & \mathbf{Y}^2 \end{pmatrix}, \quad (\breve{\mathbf{X}},\breve{\mathbf{Y}}) = \begin{pmatrix} P^1\mathbf{X}^1 & P^1\mathbf{Y}^1 \\ P^2\mathbf{X}^2 & P^2\mathbf{Y}^2 \end{pmatrix}.$$

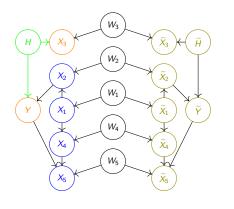
Use  $(\mathbf{X}, \mathbf{Y})$  as a substitute for  $(\mathbf{X}, \mathbf{Y})$ .

#### **OLS:** Baseline

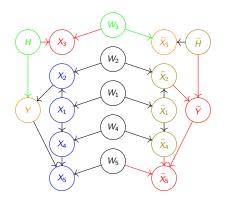
$$\beta^{\text{OLS}} := \left(\sum_{k=1}^{K} \text{cov}(X^k)\right)^{-1} \sum_{k=1}^{K} \text{cov}(X^k, Y^k)$$
$$\hat{\beta}^{\text{OLS}} := (\mathbf{X}^t \mathbf{X})^{-1} \mathbf{X}^t \mathbf{Y}$$

Method: Variable with largest  $\hat{\beta}^{OLS}$  value is taken as most likely parent or ancestor.

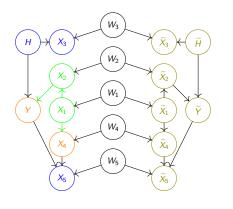




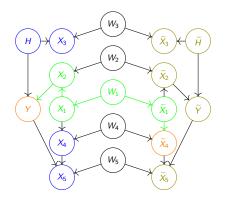
Y and  $X_3$  confounded by H



Y and  $X_3$  confounded by H but  $Y \perp X_3$  by global Markov

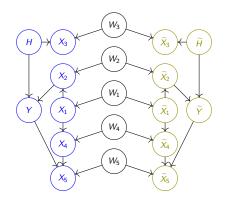


Y and  $X_4$  confounded by  $X_1$ 



Y and  $X_4$  confounded by  $X_1$  and  $Y \not\perp\!\!\!\perp_{\mathcal{G}} \widetilde{X}_4$ 

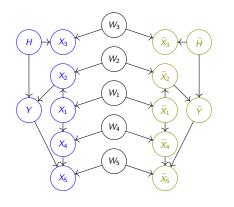
## Strong Reichenbach's Common Cause Principle



 $Y \not\perp_{\mathcal{G}} \widetilde{X}_i$  if and only if

- ► there is a **non-hidden** confounder  $X_{\ell}$  of Y and  $X_{i}$ , or
- $ightharpoonup X_i$  is an ancestor of Y

## Strong Reichenbach's Common Cause Principle



 $X_i \not\perp_{\mathcal{G}} \widetilde{X}_i$  if and only if

- ► there is a **non-hidden** confounder  $X_{\ell}$  of  $X_{j}$  and  $X_{i}$ , or
- $\triangleright$   $X_i$  is an ancestor of  $X_i$ , or
- $ightharpoonup X_i$  is an ancestor of  $X_i$

#### Novel methods

Break hidden confounding by using

 $\widetilde{Y}^k$  instead of  $Y^k$ , or  $\widetilde{X}^k$  instead of  $X^k$ .

# POLS: Learning from unpaired data

$$\beta^{\text{POLS}} := \left(\sum_{k=1}^{K} \text{cov}(X^k)\right)^{-1} \sum_{k=1}^{K} \text{cov}(X^k, \widetilde{Y}^k)$$
$$\hat{\beta}^{\text{POLS}} := (\mathbf{X}^t \mathbf{X})^{-1} \mathbf{X}^t \widetilde{\mathbf{Y}}$$

Method: Variable with largest  $\hat{\beta}^{POLS}$  value is taken as most likely parent or ancestor.

# **DPOLS:** Learning from paired data

$$\beta^{\text{DPOLS}} := \left(\sum_{k=1}^{K} \text{cov}(X^k, \widetilde{X}^k)\right)^{-1} \sum_{k=1}^{K} \text{cov}(X^k, \widetilde{Y}^k)$$
$$\hat{\beta}^{\text{DPOLS}} := (\mathbf{X}^t \widetilde{\mathbf{X}})^{-1} \mathbf{X}^t \widetilde{\mathbf{Y}}$$

Method: Variable with largest  $\hat{\beta}^{\mathrm{DPOLS}}$  value is taken as most likely parent or ancestor.

# DPOLS finds correct parents given distribution

$$cov(X^k, \widetilde{Y}^k) = cov(X^k, \beta^t \widetilde{X}^k + \gamma^t \widetilde{H}^k + \widetilde{N}_{\widetilde{Y}^k}) = cov(X^k, \widetilde{X}^k)\beta$$
so

$$\beta^{\text{DPOLS}} = \left(\sum_{k=1}^{K} \text{cov}(X^k, \widetilde{X}^k)\right)^{-1} \sum_{k=1}^{K} \text{cov}(X^k, \widetilde{Y}^k)$$
$$= \left(\sum_{k=1}^{K} \text{cov}(X^k, \widetilde{X}^k)\right)^{-1} \sum_{k=1}^{K} \text{cov}(X^k, \widetilde{X}^k)\beta$$
$$= \beta$$

(argument from unpublished notes by Niklas Pfister)

### Simulating data

- 1. Simulate 1000 random DAGs and coefficient matrices
- 2. Choose data parameters (number of observations, etc.)
- 3. Simulate data sets from the 1000 DAGs using parameters

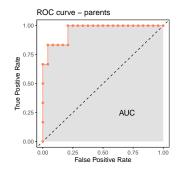
# Fixed parameters in this presentation

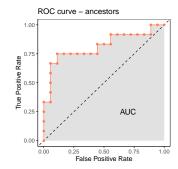
30 X's and 30 H's

$$egin{aligned} N_{Y_j^i}, N_{X_j^i}, \widetilde{N}_{\widetilde{Y}_j^i}, \widetilde{N}_{\widetilde{X}_j^i} &\overset{ ext{iid.}}{\sim} \mathcal{N}(0, 1) \ N_{H_j^i}, \widetilde{N}_{\widetilde{H}_j^i} &\overset{ ext{iid.}}{\sim} \mathcal{N}(0, 5^2) \ W_j^i &\overset{ ext{iid.}}{\sim} \mathcal{N}(0, 7^2) \end{aligned}$$

# **Evaluating the methods**

- **1.** For all  $n \in \{0, ..., \#X\}$ 
  - **a.** Select *n* highest ranked variables.
  - **b.** Calculate true positiveand false positive rates.
- 2. Draw ROC curve
- **3.** Calculate AUC
- 4. Average 1000 AUCs



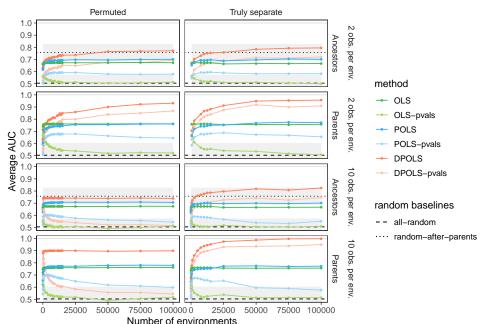


#### Random baseline methods

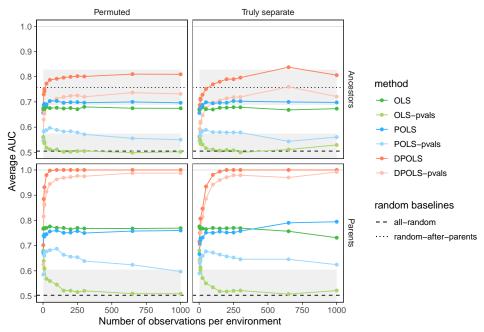
**all-random**Random ranking of variables.

random-after-parents
Ranks correct parents highest;
ranks remaining variables in
random order.

#### Performance of methods for varying number of environments



#### Performance of methods for varying number of obs. per environment.



#### **Conclusions**

- ► DPOLS
  - selects correct parents asymptotically on truly separate data
  - ▶ performs well on permuted data
  - ▶ is able to select some extra ancestors after selecting all parents
- ► POLS
  - ▶ is viable for causal discovery from unpaired data
  - ▶ is not as good as DPOLS on paired data

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- ► POLS
  - ▶ is viable for causal discovery from unpaired data
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#### Future work:

How many variables to select?